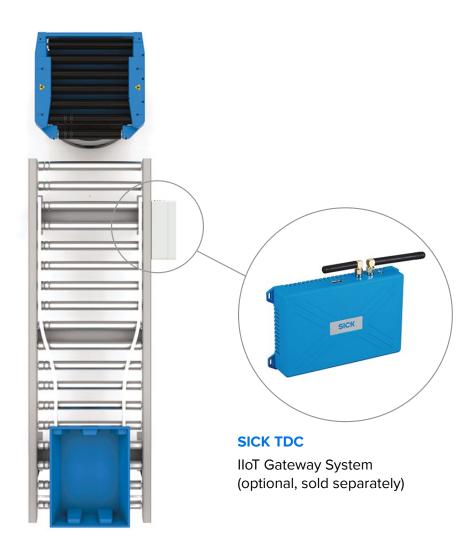
Zebra Robotics Automation™





SICK TDC Smart Gateway

The SICK Telematic Data Collector (optional, sold separately) is a networked industrial I/O device that serves as a bridge between the FetchCore and other industrial equipment such as conveyors, doors and air showers. Automate hand-offs between RollerTop robots and active powered conveyors by connecting a SICK TDC to any conveyor controller.





Coexist with Current Conveyor Infrastructure

Conveyor systems have dramatically increased industrial efficiency for many years. However, these fixed assets are hard to adapt to today's everchanging material transport requirements. Zebra's RollerTop solution brings adaptability and increased levels of automation in these conveyor environments.



Specifications	RollerTop
Weight	186.2 lbs. (84.5 kg) Add'l weight with riser installed: Riser 1: 5.5 lbs. (2.5 kg) Riser 2: 6.7 lbs. (3.0 kg)
Supported Conveyor Heights	18 in. (45.7 cm) or 22.75 in.—30 in. (57.8 cm—27.2 cm) in 0.25 in. (6.35 mm) increments
Maximum Payload	Up to 176 lbs. (80 kg) (depends on configuration)
Base Footprint	23.6 in. (59.9 cm) length, 21.7 in. (55.1 cm) width
Cargo Dimensions	20.6 in.—32.7 in. (52.3 cm—83.0 cm) (depends on riser height)
Maximum Speed	3.9 mph (1.75 m/s)
Turning Radius	Turn in place
Nominal Continuous Runtime	~9 hrs
Environment	Indoors
Charging	Autonomous docking
Charge Time	3 hrs to 90%
2D Laser Sensor	SICK, 82 ft. (25 m), 220°
3D Camera	Yes (x2)

Key Workflows



Order Picking



Assembly and QA



End of Line Handling



ASRS Induction



Rush Orders





WARNING: This product uses components which emit invisible laser radiation. Incorrect use or observing the safety laser scanner through optical instruments (such as magnifying glasses, lenses, telescopes) may be hazardous for the eyes.



ANSI/RIA R15.08 Zebra AMRs conform with R15.08 safety standards published by the RIA (Robotics Industry Association)

For more information about Zebra's autonomous mobile robot solutions, please visit www.zebra.com



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